# **Applied differential Equations**

## Day 1: Intro and Notations

## **Definition:**

Equations containing derivatives are differential equations.

**Examples: 0.1.** 1.  $y' = t^2 + 2$  2.  $y'' + 4y' = \cos x$  3.  $y''' + 2(y')^3 + \sin x = 4$ 

#### **Terminology**(**Definitions**)

• Ordinary differential equation: An ordinary differential equation (ode) is an equation between one independent variable, one dependent variable and the derivative(s) of the independent variable.

**Examples: 0.2.**  $y' = y^2 + t$  is an ode. An example of a partial differential equation is  $u_{tt} = u_x$  or Heat equation:  $u_t = cu_{xx}$ Here the unknown dependent variable u(x, t) is a function of both x and t.

• A solution to an ode is a function of the independent variable that can be plugged in for dependent variable in the equation.

Examples: 0.3. 1. 
$$y = \frac{t^3}{3} + 2t + 5$$
 is a solution for  $y' = t^2 + 2$  because  $\underbrace{\left(\frac{t^3}{3} + 2t + 5\right)'}_{y'} = t^2 + 2$ .

2. 
$$y = \sin(2x) + \frac{\cos(x)}{3}$$
 is a solution for  $y'' + 4y = \cos x$ , because  
$$\underbrace{\left(\sin(2x) + \frac{\cos(x)}{3}\right)''}_{y''} + \underbrace{4\left(\sin(2x) + \frac{\cos(x)}{3}\right)}_{4y} = \cos(x).$$

• Order: The order of an ode is the order of the highest derivative in the equation.

Examples: 0.4. In Example 0.1 : 1: is of order 1 and 2 is of order 2 and 3 is of order 3.

• Linear: A linear ode is one in which the dependent variable and its derivatives appear linearly.

**Examples: 0.5.** 1.  $y' = y \sin t + \ln t$  is a linear ode:

This is a linear ode even though there are terms sin(t) and ln(t). The independent variable t can appear nonlinearly in a linear ode.

2.  $y' = t \sin(y)$  is a non-linear ode because y is non-linear in  $\sin(y)$ .

The general form of a linear ode is  $P_n(t)\frac{d^n}{dx^n}y + P_{n-1}(t)\frac{d^{n-1}}{dx^{n-1}}y + \dots + P_0(t) = 0$ The general form of a 1st-order linear ode is

y' + p(t)y = g(t)

• Autonomous ode: For an autonomous ode f(t, y) is a function of y only. That is y' = g(y).

**Example 0.6.**  $y' = \underbrace{y(1-y)}_{\text{Finction of y-only}}$  is an autonomous ode.

#### **Definition:**

The expression representing <u>all possible solutions</u> to the ode and is called the **general solution**. The geometrical representation of the general solution is a family of infinitely many curves called **integral curves**. Each curve is associated with one value of the integration constant.

### General Form of a first-order ode

The general form of a first-order ordinary differential equation is

y' = f(t, y)

or

 $y' = f(t, y), y(t_0) = y_0$ 

 $y(t_0) = y_0$  is the initial condition which determines the value of integration constant.

#### Note:

Here t is the independent variable and y(t) is the dependent variable. The goal is to determine the unknown function y(t)

The solution to the equation whose derivative satisfies the above condition and which passes through the point  $(t_0, y_0)$ 

**Example 0.7.** The solution to initial value problem  $y'(t) = t^2 + 2$ , y(3) = 5 is

$$y(t) = y(3) + \int_{3}^{t} (s^{2} + 2)ds = 5 + (s^{3}/3 + 2s)\Big|_{3}^{t} \qquad \qquad \boxed{y(t) = t^{3}/3 + 2t - 10}$$

#### **Direction/Slope Fields for First-Order ode**

Qualitative analysis is useful tool to verify numerical or analytic solutions. Even if an explicit formula is known, qualitative analysis is useful, since it can give a visual picture of the behavior of solutions to an ode.

One method of estimating the solutions to a differential equation is using the Direction/slope fields.

For a first order differential equation, we can calculate the slope of tangent line at any point (x, y) on the plane. To obtain a **direction field** choose various points on a grid then, at each point draw line segments with slopes of tangent line at that point.

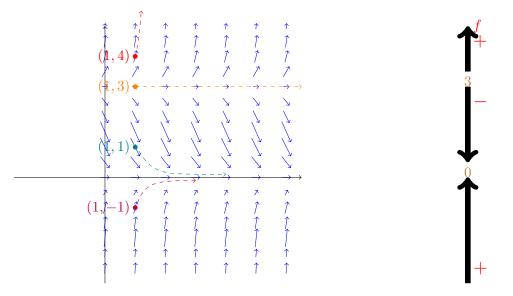
**Example 0.8.** Use slope fields to find the solution to equations y' = y(y-3) at the following initial values:

- *I.* y(1) = 4 *3.* y(1) = 1
- 2. y(1) = 3 4. y(1) = -1

First calculate the slopes at few different (x, y) values: Hint: the critical values are y = 0 and y = 3 so include them.

(x,y)	y' = y(y-3)								
:	:	:	:	:	:	:	:	:	÷
(0, -2)	y' = 10	(1, -2)	y' = 10	(2, -2)	y' = 10	(3, -2)	y' = 10	(4, -2)	y' = 10
(0, -1)	y' = 4	(1, -1)	y' = 4	(2, -1)	y' = 4	(3, -1)	y' = 4	(4, -1)	y' = 4
(0,0)	y' = 0	(1,0)	y' = 0	(2, 0)	y' = 0	(3,0)	y' = 0	(4,0)	y' = 0
(0,1)	y' = -2	(1,1)	y' = -2	(2, 1)	y' = -2	(3,1)	y' = -2	(4,1)	y' = -2
(0,2)	y' = -2	(1,2)	y' = -2	(2, 2)	y' = -2	(3,2)	y' = -2	(4, 2)	y' = -2
(0,3)	y' = 0	(1,3)	y' = 0	(2, 3)	y' = 0	(3,3)	y' = 0	(4,3)	y' = 0
(0,4)	y' = 4	(1,4)	y' = 4	(2, 4)	y' = 4	(3,4)	y' = 4	(4, 4)	y' = 4
:	÷	÷	:	:	÷	:	÷	:	÷

Then graph a small line segment with those slopes at each (x, y);



Last start at each initial and see if you can find a solution. (The dashed lines are my approximations.) If you use more points for the slope field, you get a better approximation.

### **About Equilibrium Solutions:**

- 1. What are the equilibrium solutions? y = 0 and y = 3 where it seems that if the initial value is placed on either, the solution remain on that line.
- 2. Which of the equilibrium is a stable equilibrium? y = 0. The solutions seem to diverge from y = 3 but converge to y = 0 from surrounding initial points.